

# **OCEANIC INSTALLER**



The DSV "OCEANIC INSTALLER" is a multipurpose worldwide offshore construction, maintenance and diving support vessel, equipped with a passive stabilising system, fully redundant dynamic positioning system, saturation and surface supplied diving systems, Triton WROV and Viper ROV, heavy lifting equipment and helideck.

The OI was designed and built by ULSTEIN HATLO in 1984. The diving system was designed and installed by SUBSEA OFFSHORE Ltd. The DP system was designed by A/S KONGSBERG. The Lifting equipment includes a LIEBHERR high capacity deck crane with a boom length of 37.5m and a maximum lift of 100Te.

#### Dimension

Overall length	84.00 m
Moulded Breadth	18.80 m
Moulded Depth	7.10 m
Summer Draught	4.66 m

# Performance and Propulsion

11 knots
1803 T
600 m <sup>2</sup>
240 m <sup>3</sup>
19 m dia (Super Puma)

### Capacities

Bunkers	545 m³
Fresh Water	500 m³
Ballast Water	1800 m³

### Machinery

Main engines	2 x 2640 hp
Main propellers	2 x 1800 hp (controllable pitch)
Generators	440 V-60 Hz
Shaft driven	2 x 1570 kVA
Diesel driven	3 x 625 kVA

### Thrusters

Bow Thruster	3 x 150 TV Type, Ulstein 800HP
Stern Thruster	2 x 150 TV Type, Ulstein 800HP

## **Fuel Consumption**

At max speed of 11 knots	14m³/day
At economical speed of 9 knots	12m³/day
In DP mode	11M <sup>3</sup> /day

#### Classification

№1A1 HELDK DSV-III EO DYNPOS-AUTR

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### **Dynamic Positioning System**

Fully redundant KONGSBERG Dp system type SDP 521 – DP Class II

**Reference Systems** 

2 x taut wire Sonardyne USBL Fanbeam 4.2 2 x DGPS

DP control system governs three forward and two aft transverse thrusters, the two main propellers and two rudders.

#### Cranes and Winches

Main Crane:	
Main hoist	100 T at 8.9 m
Whip hoist	12 T at 10.5 m
Service crane	9 T at 2 m
Main Deck IMECA Winch	120 T double drum

#### **Mooring System**

Main anchors	2 x 7 T
Chain length	1 x 440m, 1 x 385m

#### Diving

Saturation diving system of max 14 men to 230 m (SW) Moonpool-launched 3-man diving bell Side-launched air surface dive system 16-man hyperbaric rescue capsule

#### ROV

- 1 x Work ROV Triton 100 hp rated 3000 m with set of tools
- 1 x light Work ROV Viper 25 hp



### Communication

Satellite Communication

VSAT 800 Ku band

#### Accommodation

Berths

POB 88 / Project Personnel 56 Fully equipped Hospital & Recreation facilities

## **Diving Equipment**

The diving system was designed and supplied by SUBSEA OFFSHORE Ltd.

The saturation diving system is a 750ft (230m) depth rated DNV classified system with a maximum capacity of 14 men in 3 habitat chambers. The chambers are configured to give 24 hour diving at split vessels in addition to decompression capability.

A 16-man Hyperbaric Evacuation Capsule (HEC) is on main deck starboard side, and is launched by an A-frame which is self-powered from a hydraulic accumulator system.

The 3-man diving bell is launched through a centrally positioned Moonpool. The hydraulically powered handling system includes a traversing trolley, main bell winch, powered umbilical winch, guide wire and clump weight system. To aid bell launch and recovery operations, Moonpool is fitted with especially designed baffles to dampen water motion.

The vessel has a gas storage capacity of approximately 450,000 ft<sup>3</sup> (12,750m<sup>3</sup>) under main deck. Gas supply and management systems will provide for gas transfer, mixing and supply to the saturation control centre and dive control room.

A separate air dive control station controls all operations and communications for surface supplied diving. Instrument layout is sophisticated and compact, leaving ample room for inspection engineers and Client personnel.

The saturation control centre contains all controls, monitors and communication systems for the complete chamber complex. A direct phone link to dive control room and a closed circuit TV system ensure a full coordination during bell lock on / off operations.

A skid-mounted air diving system is installed for working down to 165ft (50m). It comprises a 2-man dive basket, a hydraulically operated A-frame and air powered man-riding winches (basket and clump weight). An air decompression chamber is adjacent for surface decompression and therapeutic use.



Disclaimer: Specification is subject to change at owner's discretion

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